MECHATRONICS

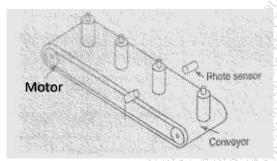
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| | | [Time: 3 Hours] | 80] |
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| | N.B: | Please check whether you have got the right question paper. 1. Question No.l is compulsory 2. Attempt any three questions out of remaining five questions 3. Figures to right indicate full marks 4. Assume suitable data if necessary 5. Notations carry usual meaning | |
| Q.1 (A) | 1) Piezoele | al Asynchronous Receiver and Transmitter (UART) oil actuator gers | 05 |
| (B) | in hydraulio Describe po | ketch explain the constructional feature and working of pressure relief valve used a system assible speed control strategies of A.C. Induction motors rt note on servo amplifier for DC motors | 05 05 10 |
| Q.3 (A) | sequence of (AB)+ Dela Develop the valves. The Explain imp | e acting pneumatic cylinders A, B are selected for an industrial application. The f movement for piston of the cylinder is proposed as below— by B+ A- e electro-pneumatic circuit using 5/2 double solenoid as final directional control piston motions mentioned in bracket is simultaneous. bedance matching for a part of electro-mechancial system that consists of on of power using motor-gear drive system. | 08 |
| (B) | Managemen With neat d pneumatic | liagrams illustrate the working of Filter-Regulator- Lubricator (FRL) unit in a | 10 05 05 |
| Q.5 (A) | bottles com of the bottle i)The start | motor is required to program using a PLC in a process line based on the number of sing off the conveyor as shown in Figure I.A photo-sensor is used to sense the passage. Develop a PLC ladder logic diagram for the following sequential tasks pushbutton can be pressed to start the conveyor move past the photo-sensor and the conveyor motor stops automatically after | ge |

count of 25 bottles.

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iii) The counter is to be reset to zero after 25 counts The accumulated count of the counter is reset manually by means of the count reset button



- (B) Explain the central theme of velocity profile optimization of DC motor 05 05
- (C) Explain with neat sketch principle of operation of AC induction motor
- Q.6 (A) With schematic representation explain the mechatronic system typically used in robot for 10 firefighting application (typically highlight the selection of motor, sensors and switches. Also discuss their interfacing.
 - (B) Write short note on (i) Supervisory control and data acquisition (ii) Harmonic drive 10